

# The Influence of Dynamics on Bridge Weigh-In-Motion Accuracy

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# How does a Bridge WIM Algorithm work?

**INPUT  
from  
Strain  
Sensors**

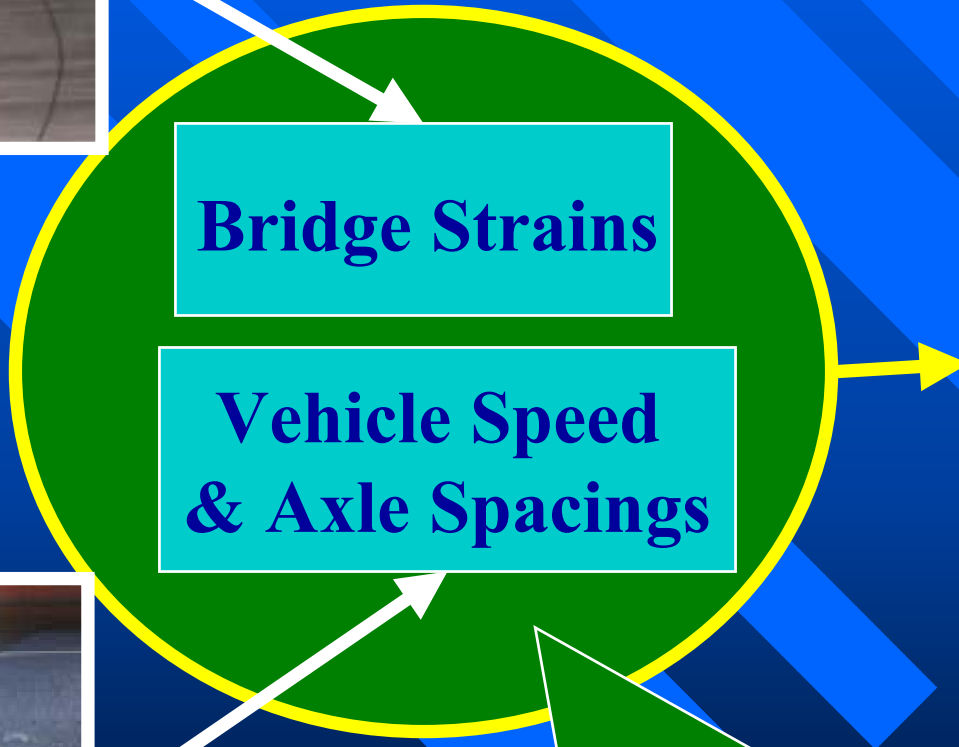
**Bridge Strains**

**Vehicle Speed  
& Axle Spacings**

**OUTPUT:  
Vehicle  
Axle  
Weights**

**INPUT  
from  
Axle  
Detectors**

**Mathematical Model of  
the Bridge Response**



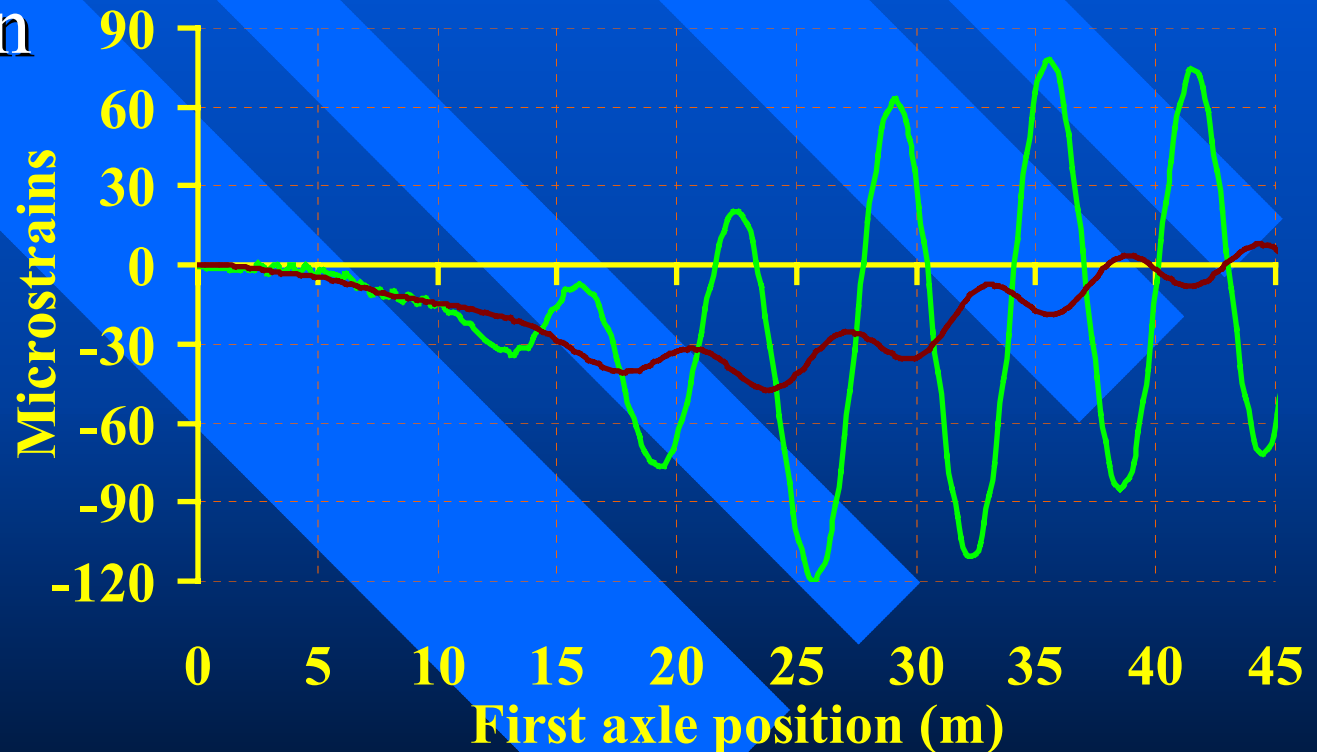
# Difficulties to Implement B-WIM

- Bridge Dimensions

- Road

Condition

— Rough Road Profile — Smooth Road Profile

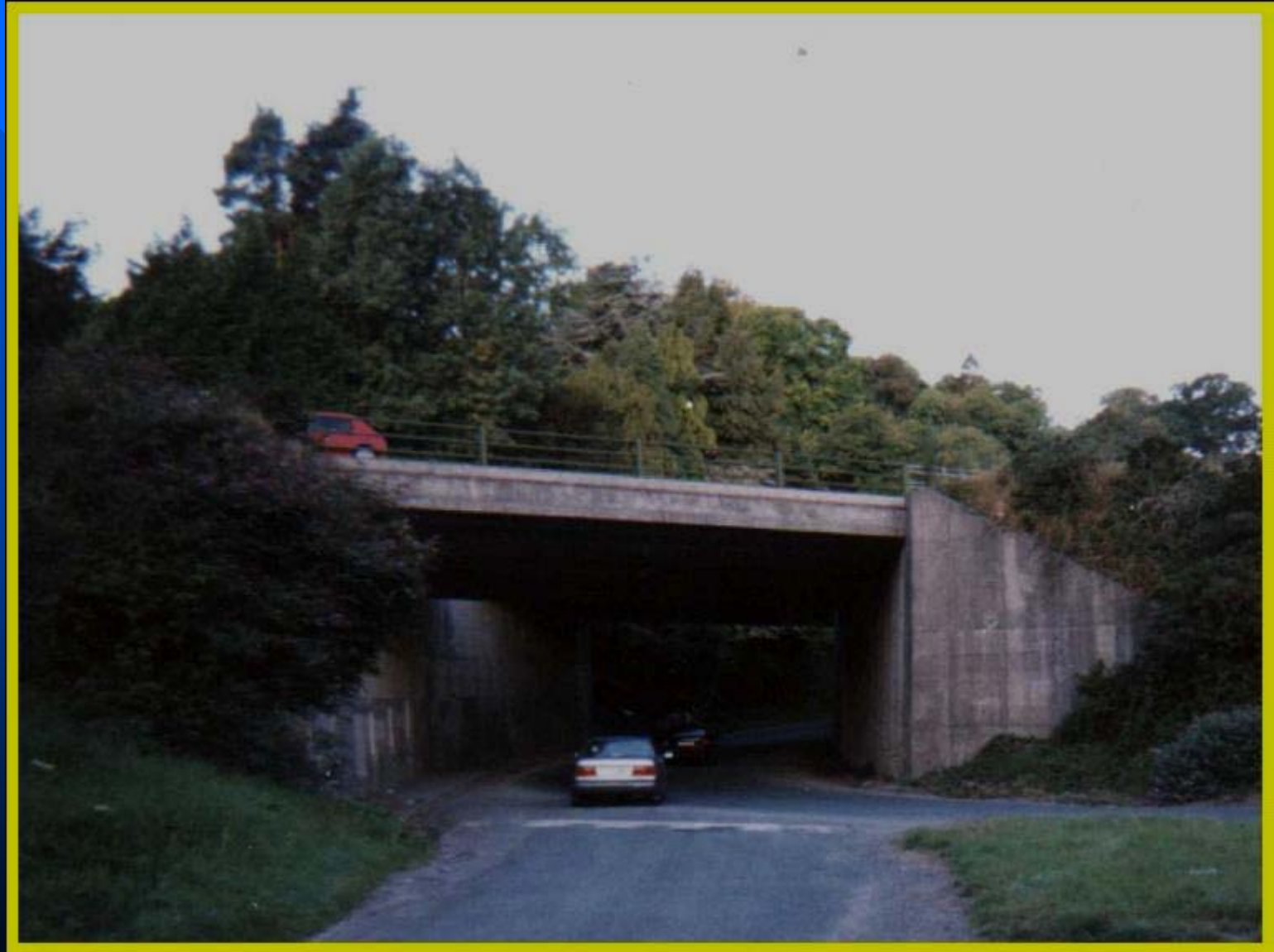


- Uncertainty on Bridge Response

# Methods to improve Accuracy

- An **Experimental Calibration**
- A Bridge WIM algorithm based on **Dynamic Equations**
- A Bridge WIM algorithm based on **Multiple Longitudinal Sensor Locations** along the bridge
- Depending on the bridge type, use of measurements **others than Longitudinal Strain at Midspan**

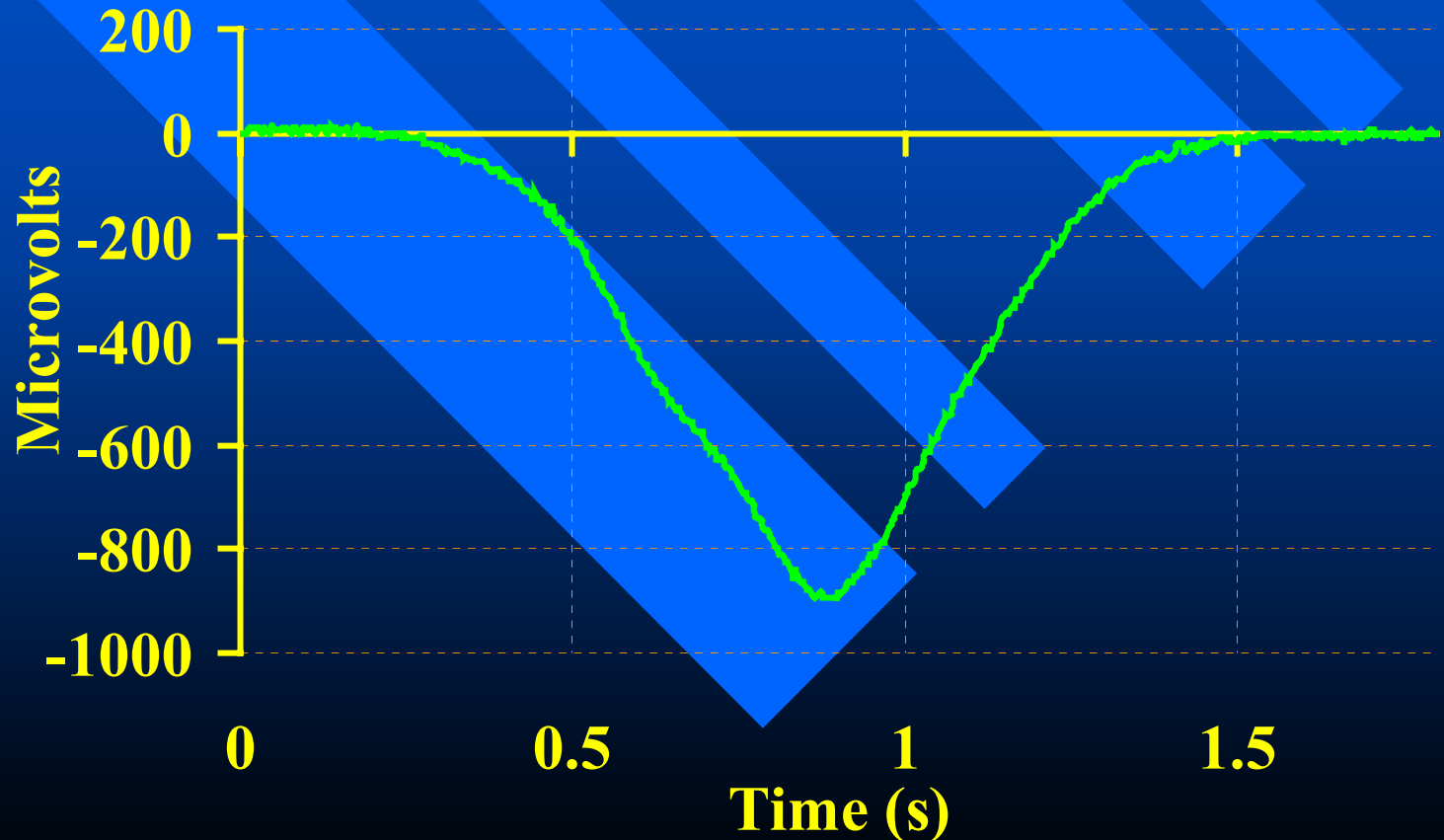
# Experimental Calibration Procedure



# Experimental Calibration Procedure

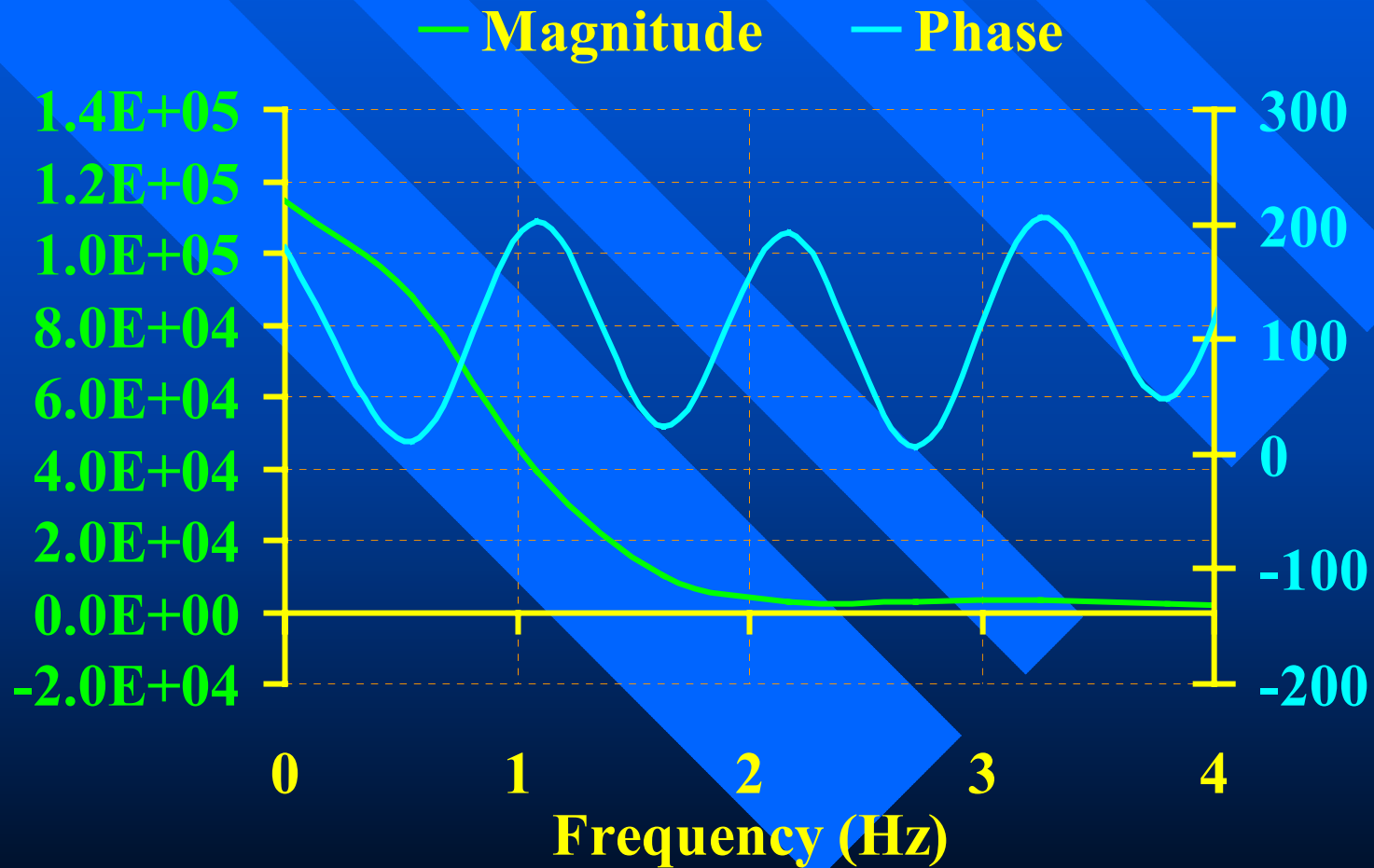
- **STEP 1:** Measure response due to vehicle of known **Speed**, **Axle Spacings** and **Static Weights**

Measured bridge response



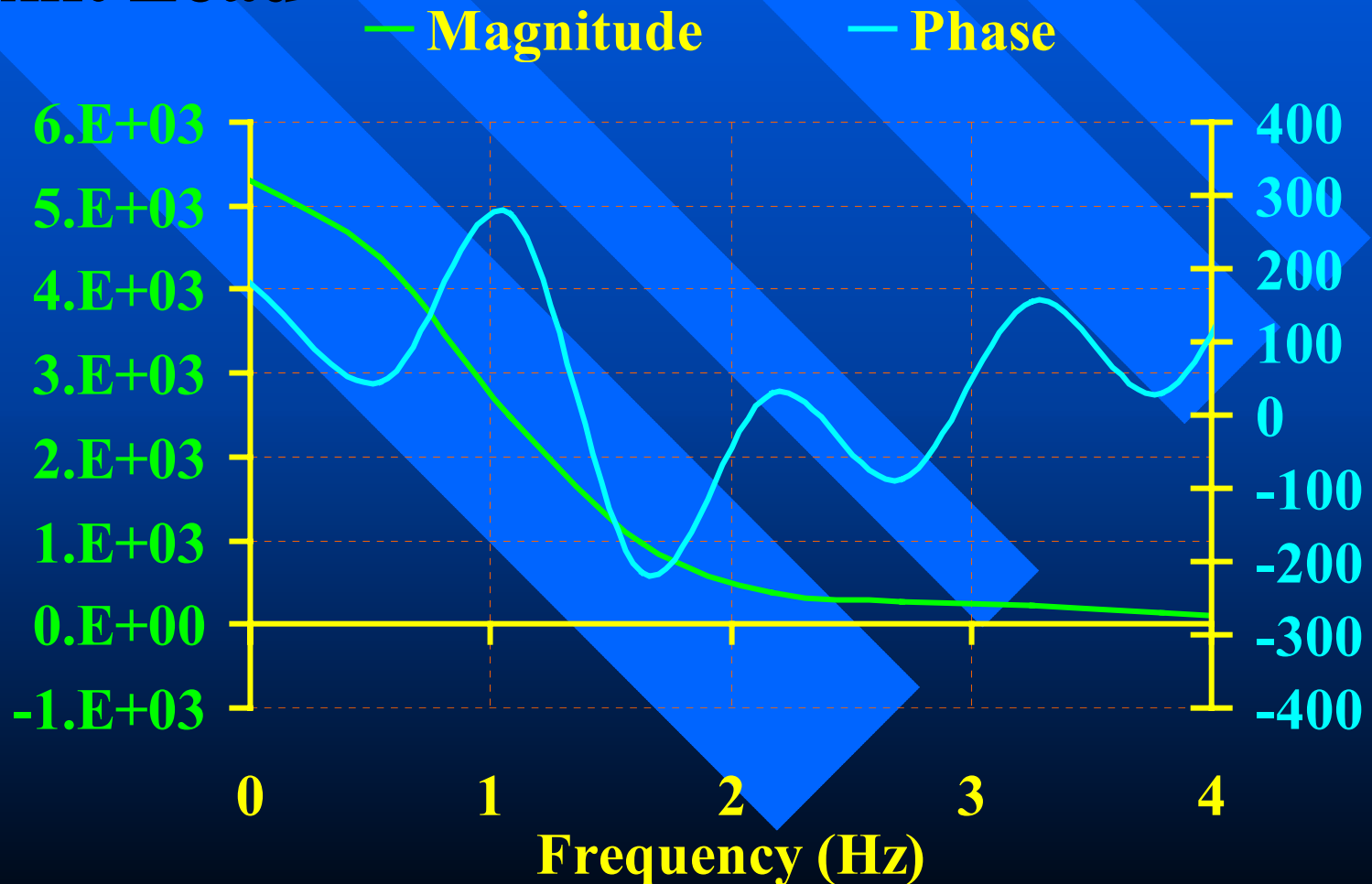
# Experimental Calibration Procedure

## ■ STEP 2: Calculate the total **Spectrum**



# Experimental Calibration Procedure

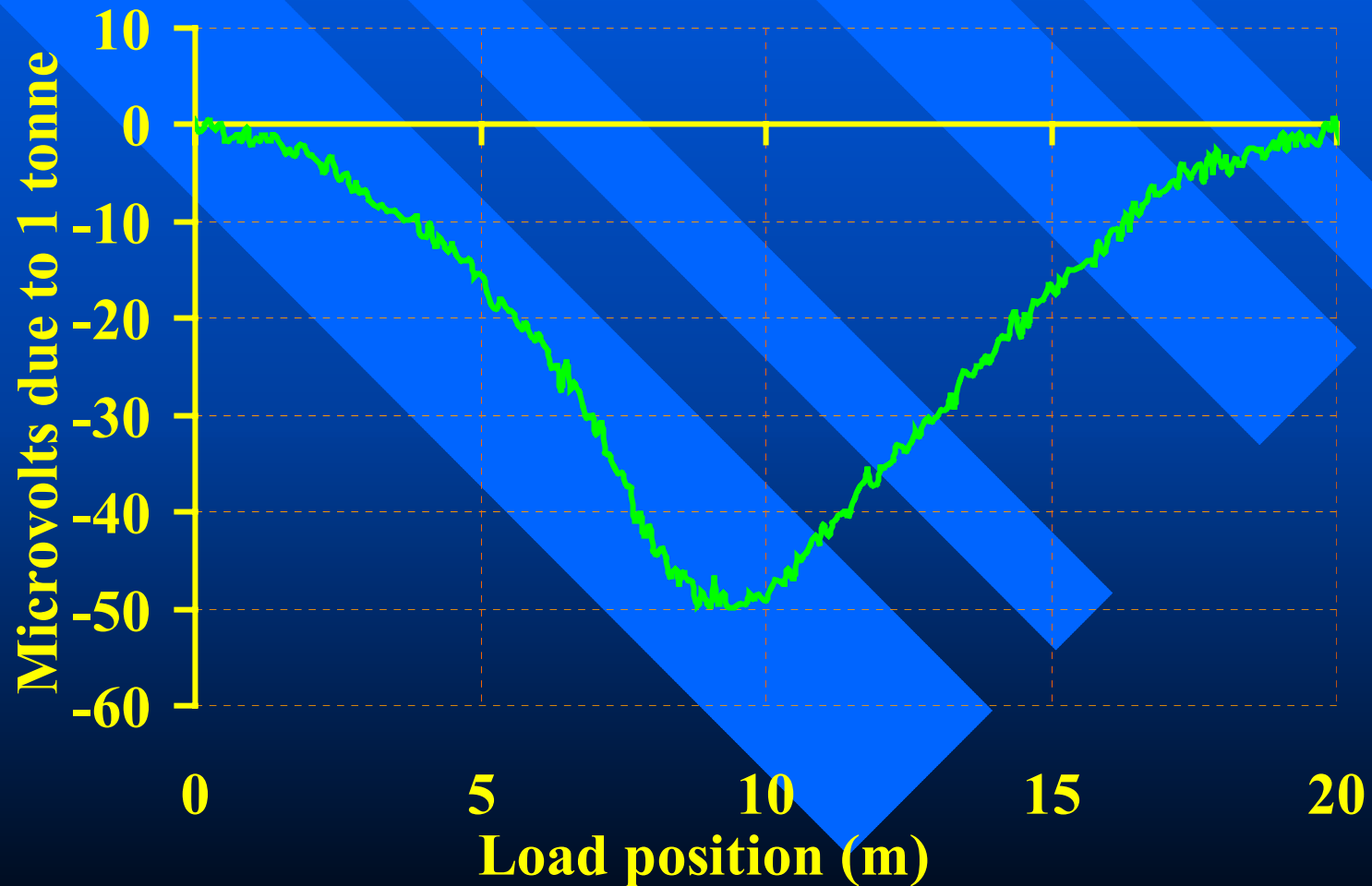
## ■ STEP 3: Calculation of the Spectrum due to a unit Load





# Experimental Calibration Procedure

## ■ STEP 4: Calculate the Influence Line



# Experimental Calibration Procedure

<b>Bridge</b> <b>15 m long</b> <b>30 degrees</b> <b>skew</b>	Test Conditions	Single Axle	Axle Group	GVW
	Extended Repeatability Conditions	C(15)	A(5)	A(5)
	Full Repeatability Conditions	A(5)	A(5)	A(5)

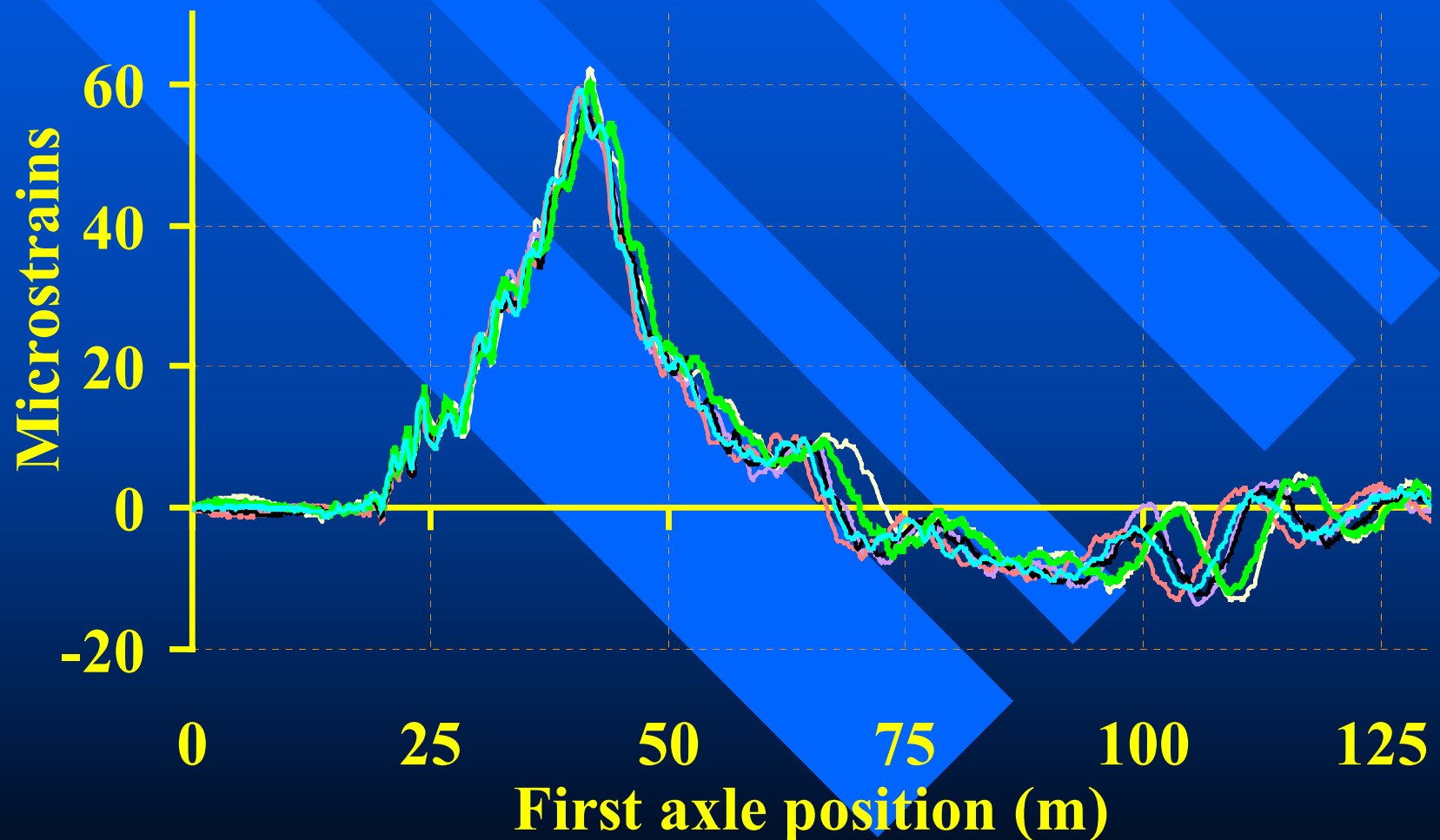
# A Dynamic B-WIM Algorithm

- **Total Strain** response compared to response from a theoretical **Bridge Dynamic Model**

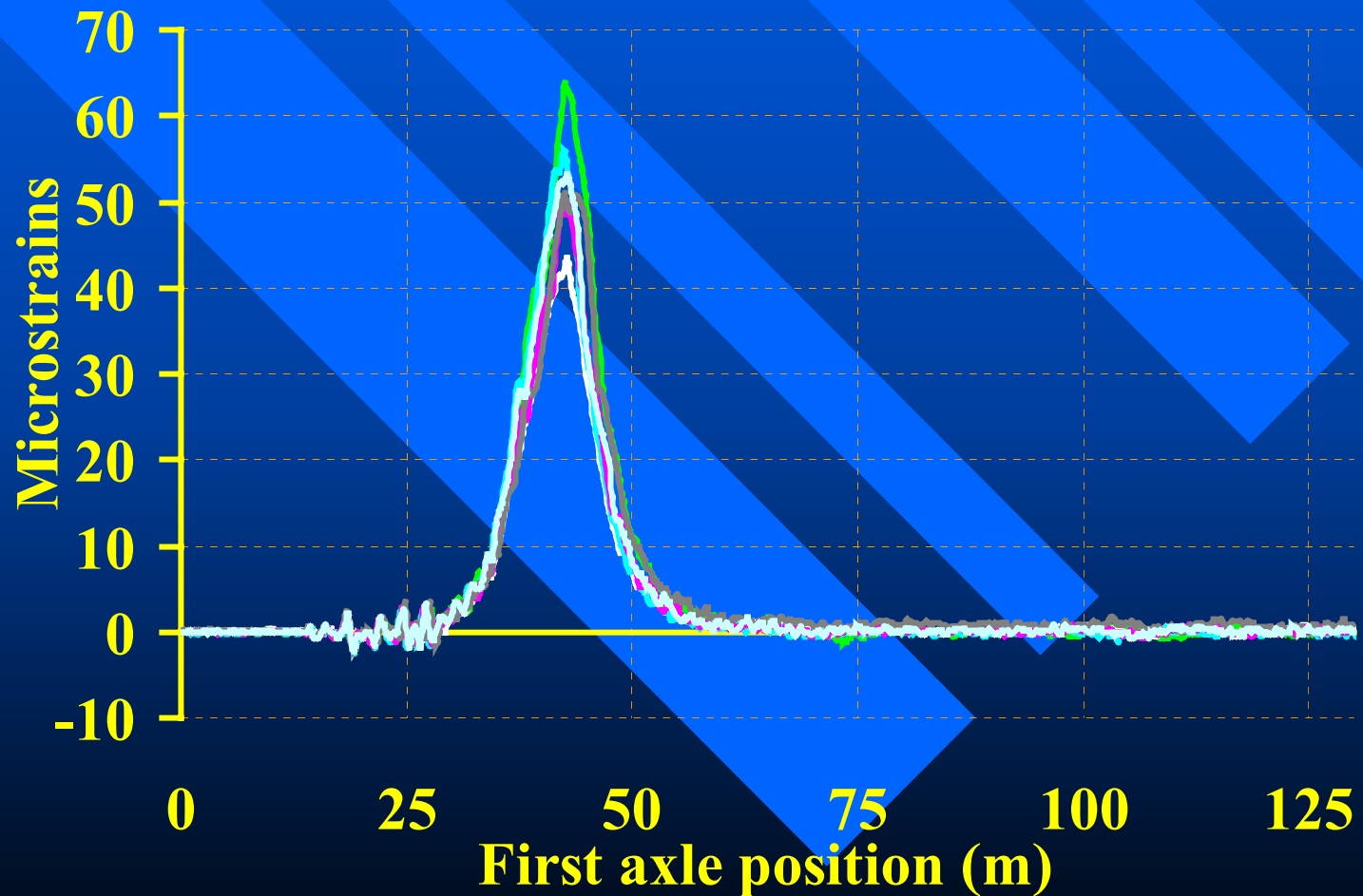


# A Dynamic B-WIM Algorithm

## Longitudinal strain at midspan



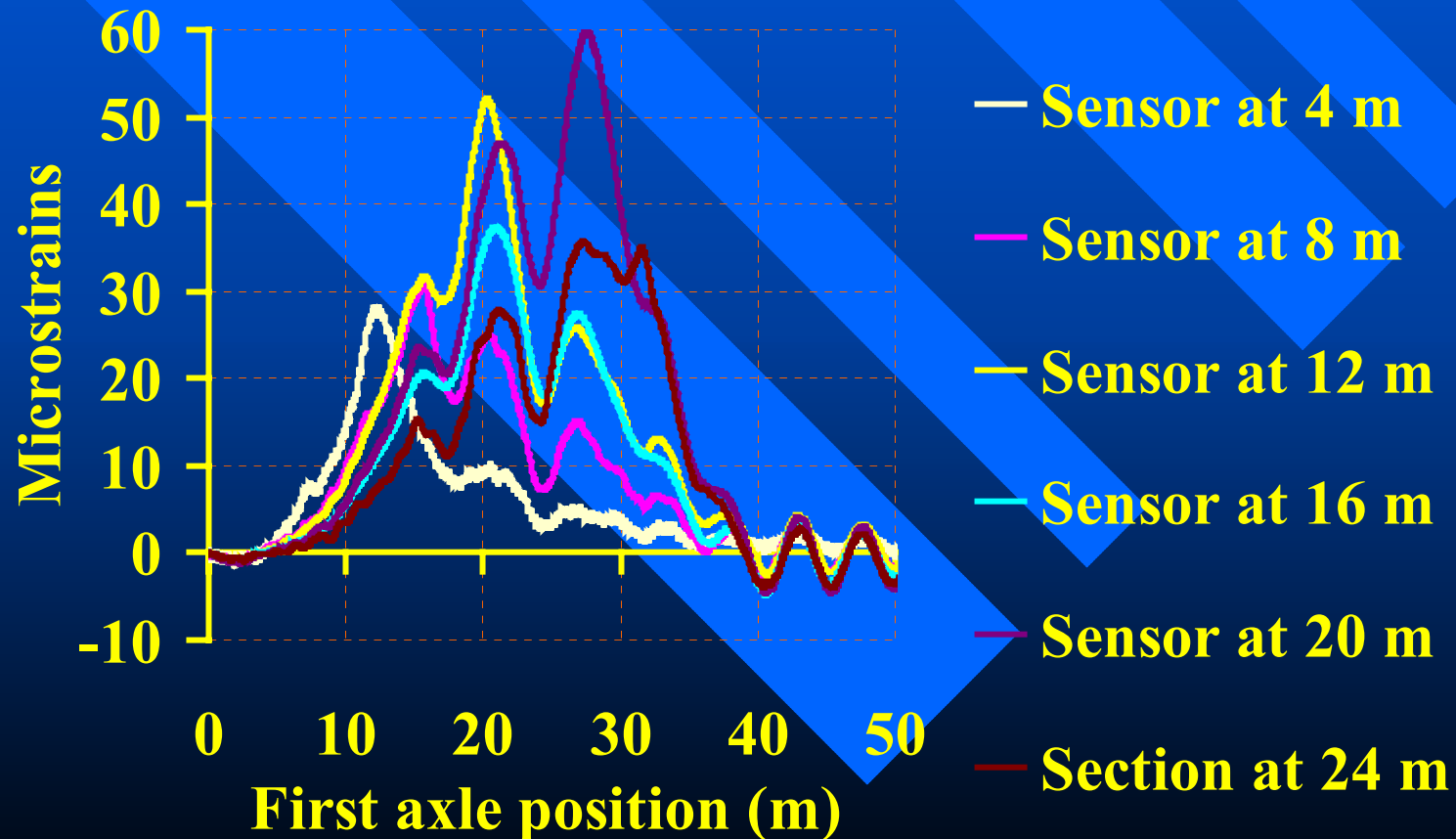
# Transverse Strain at Midspan of Box Girder Bridge



# Multiple-Sensor Bridge WIM

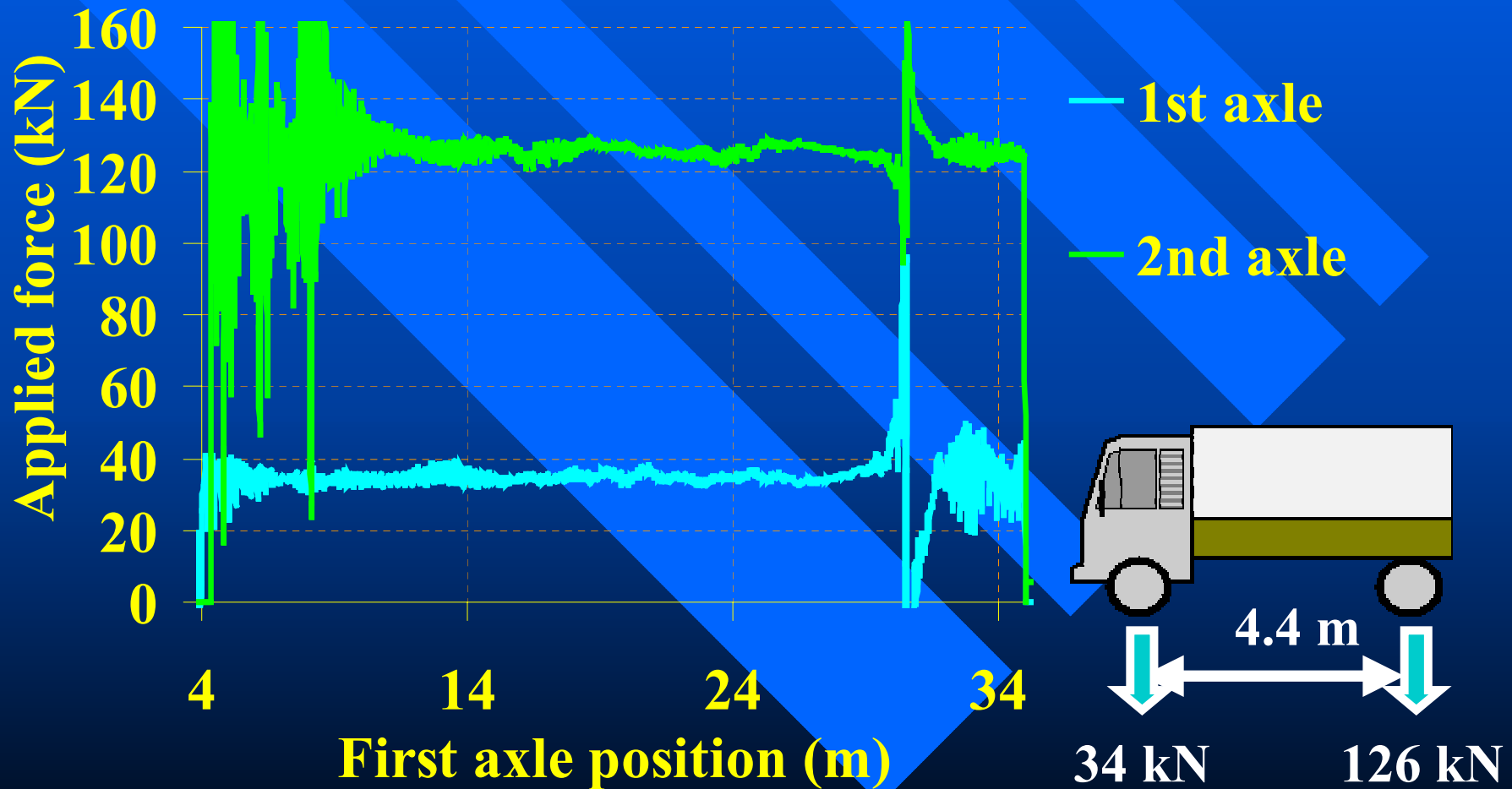
- Principle: System of equations (**One Equation for each Strain Sensor**) at each instant

Two-axle truck at 59.8 km/h



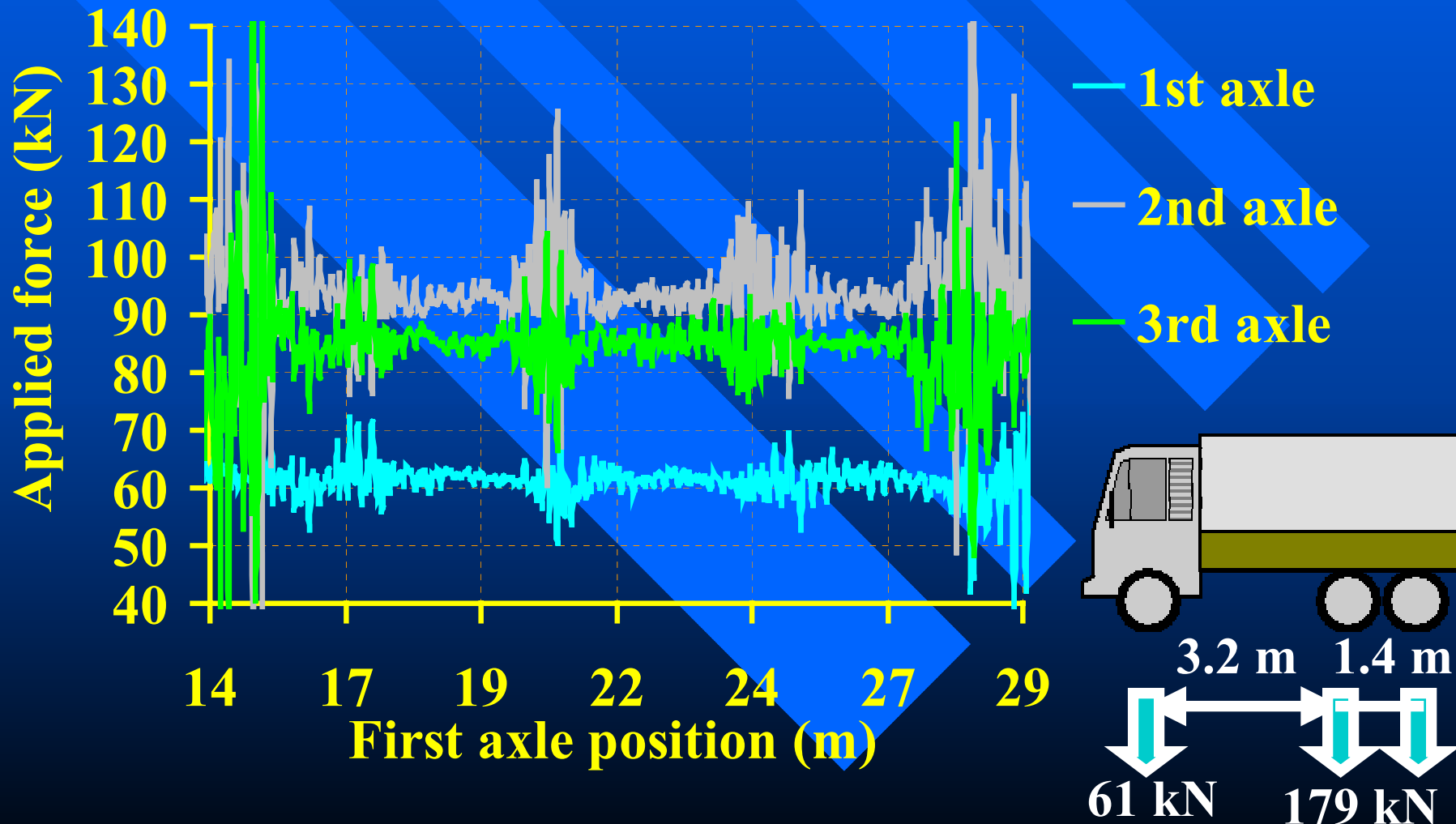
# Multiple-Sensor Bridge WIM

## Axle load history



# Multiple-Sensor Bridge WIM

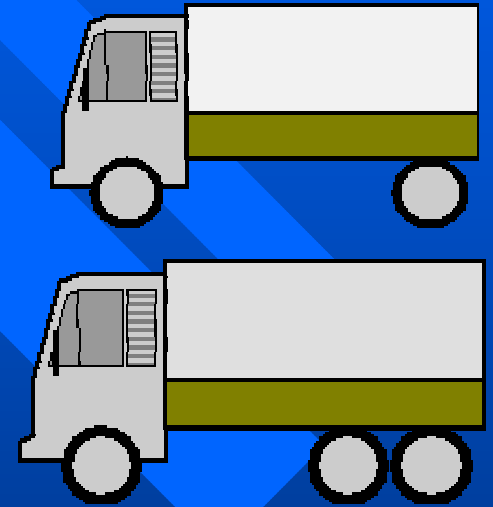
Axle load history





# Finite Element Simulations

- **Two trucks** (rigid frame 2 and 3-axles) running at **3** different **speeds** (55, 70 & 85 km/h) and **3** different **loading conditions**.



- Bridge Models:
  - A **two-Span isotropic** Slab 36 m long
  - A **Beam&Slab** Bridge 20 m long

# Accuracy Results for FE Simulations on a Two-Span Isotropic Slab

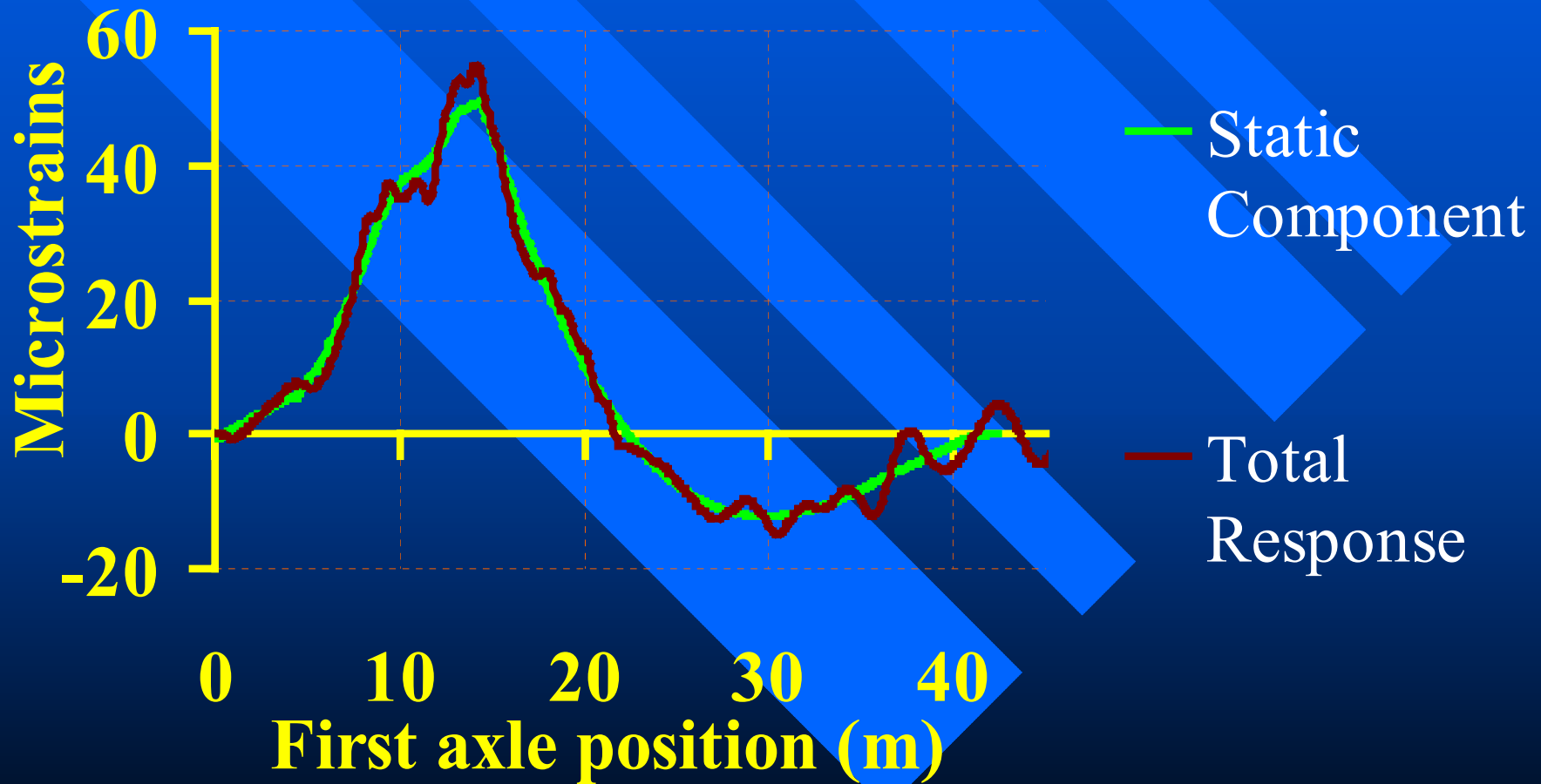
36 m long Natural Frequencies 4.2, 6.5 & 11.4 Hz	Algorithm	Single Axle	Axle Group	GVW
	STATIC based on midspan	D+(20)	B+(7)	A(5)
	DYNAMIC based on midspan	B(10)	A(5)	A(5)

# Accuracy Results for FE Simulations on a Two-Span Isotropic Bridge

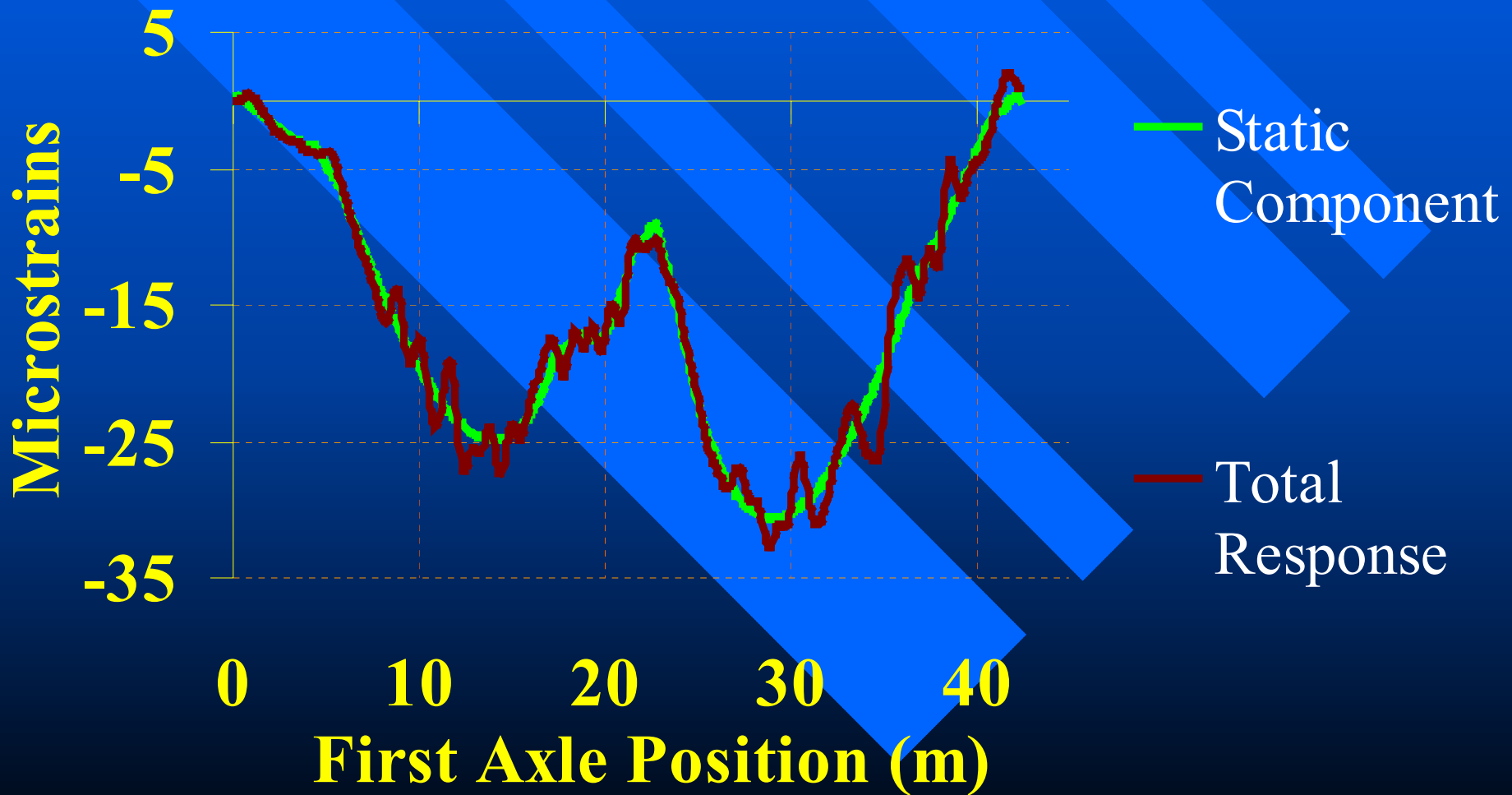
36 m long Natural Frequencies 4.2, 6.5 & 11.4 Hz	Strain	Single Axle	Axle Group	GVW
	Longitudinal bending at midspan	D+(20)	B+(7)	A(5)
	Longitudinal bending at central support	A(5)	A(5)	A(5)



# Strain at Midspan of 2-Span Bridge due to a 3-axle Truck at 70 km/h



# Strain at Central Support of 2-Span Bridge due to 3-axle Truck at 70 km/h

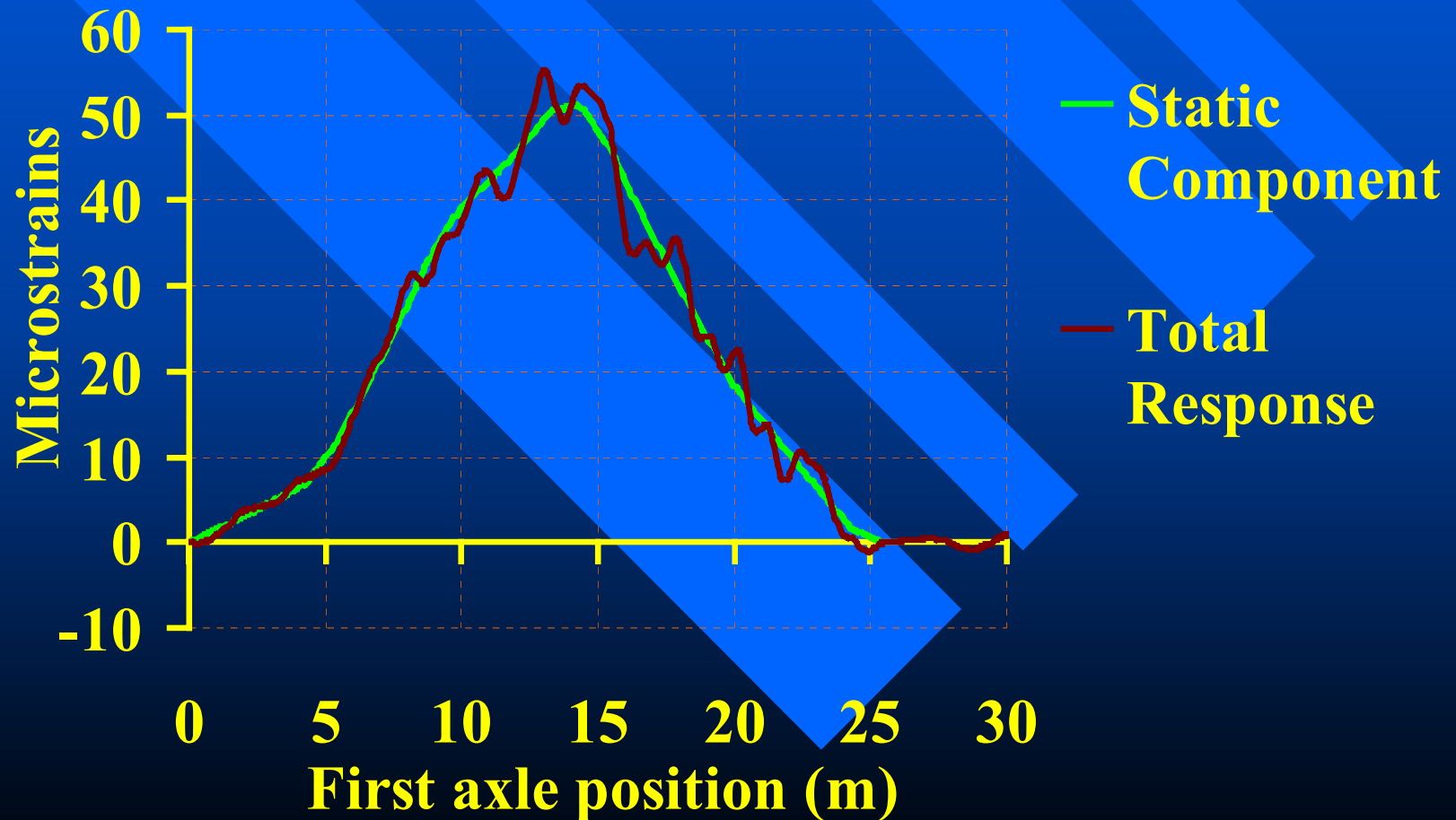


# Accuracy Results for FE Simulations on a Beam & Slab Bridge

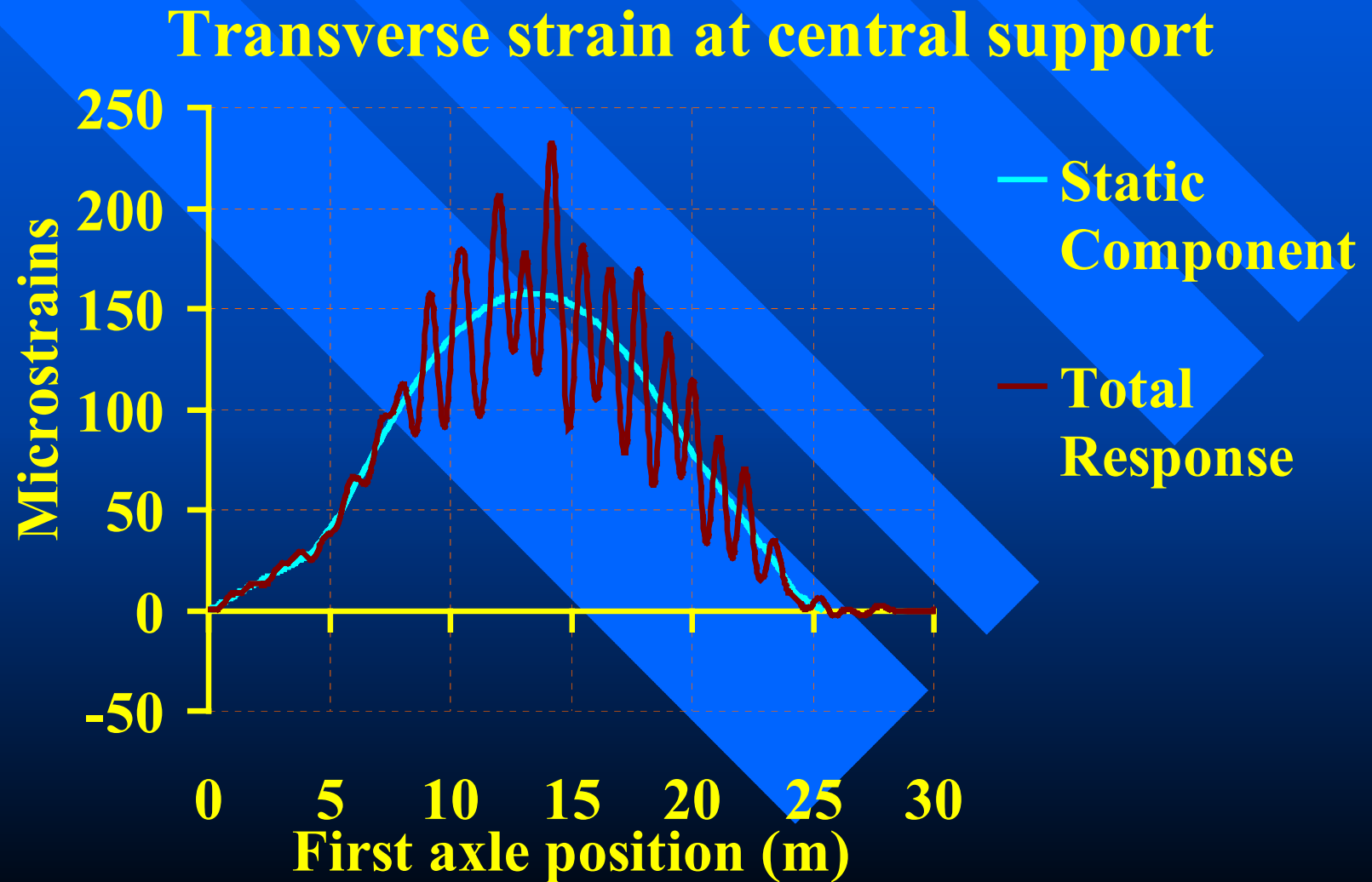
20 m long Natural Frequencies 6.1 & 7.4 Hz	Strain	Single Axle	Axle Group	GVW
	Longitudinal bending of beam/slab	B+(7)	A(5)	A(5)
	Transverse bending of Slab	A(5)	A(5)	A(5)

# Response of a Two-Span Bridge due to 3-axle Truck crossing at 70 km/h

## Longitudinal strain at midspan



# Response of Two-span Bridge due to 3-axle Truck crossing at 70 km/h





# Conclusions

- Results from using:
    - an **Experimental Calibration** Procedure,
    - a **Multiple-sensor B-WIM** algorithm,
    - the measurement of **Longitudinal Strain at the central support** of a continuous bridge,
    - and the measurement of **Transverse Strains**
- appear to improve accuracy **for some Bridge Decks** significantly and further testing is required.